



# OPERATING INSTRUCTIONS

EN

Translation of the Original

## TC 1200

Electronic drive unit

**PFEIFFER**  **VACUUM**



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## Dear Customer,

Thank you for choosing a Pfeiffer Vacuum product. Your new turbopump is designed to support you by its performance, its perfect operation and without interfering your individual application. The name Pfeiffer Vacuum stands for high-quality vacuum technology, a comprehensive and complete range of top-quality products and first-class service. With this expertise, we have acquired a multitude of skills contributing to an efficient and secure implementation of our product.

Knowing that our product must not interfere with your actual work, we are convinced that our product offers you the solution that supports you in the effective and trouble-free execution of your individual application.

Please read these operating instructions before putting your product into operation for the first time. If you have any questions or suggestions, please feel free to contact [info@pfeiffer-vacuum.de](mailto:info@pfeiffer-vacuum.de).

Further operating instructions from Pfeiffer Vacuum can be found in the [Download Center](#) on our website.

## Disclaimer of liability

These operating instructions describe all models and variants of your product. Note that your product may not be equipped with all features described in this document. Pfeiffer Vacuum constantly adapts its products to the latest state of the art without prior notice. Please take into account that online operating instructions can deviate from the printed operating instructions supplied with your product.

Furthermore, Pfeiffer Vacuum assumes no responsibility or liability for damage resulting from the use of the product that contradicts its proper use or is explicitly defined as foreseeable misuse.

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# 1 About this manual



## IMPORTANT

Read carefully before use.  
Keep the manual for future consultation.

## 1.1 Validity

These operating instructions are for customers of Pfeiffer Vacuum. They describe the function of the designated product and provide the most important information for safe usage of the product. The descriptions comply with applicable directives. All information provided in these operating instructions refer to the current development status of the product. The documentation remains valid as long as the customer does not modify the product in any way.

## 1.2 Applicable documents

TC 1200	Operating instructions
Declaration of conformity	A component of these instructions

You can find this document in the [Pfeiffer Vacuum Download Center](#).

## 1.3 Target group

These operating instructions are aimed at all persons performing the following activities on the product:

- Transportation
- Setup (Installation)
- Usage and operation
- Decommissioning
- Maintenance and cleaning
- Storage or disposal

The work described in this document is only permitted to be performed by persons with the appropriate technical qualifications (expert personnel) or who have received the relevant training from Pfeiffer Vacuum.

## 1.4 Conventions

### 1.4.1 Instructions in the text

Usage instructions in the document follow a general structure that is complete in itself. The required action is indicated by an individual step or multi-part action steps.

#### Individual action step

A horizontal, solid triangle indicates the only step in an action.

- ▶ This is an individual action step.

#### Sequence of multi-part action steps

The numerical list indicates an action with multiple necessary steps.

1. Step 1
2. Step 2
3. ...

### 1.4.2 Pictographs

Pictographs used in the document indicate useful information.





Note



Tip

### 1.4.3 Stickers on the product

This section describes all the stickers on the product along with their meaning.

		<p><b>Rating plate</b> The rating plate is located on the side of the electronic drive unit.</p>
	<p><b>Closure seal</b> The product is sealed ex-factory. Damaging or removing a closure seal results in loss of the warranty.</p>	

Tbl. 1: Stickers on the product

### 1.4.4 Abbreviations

Abbreviation	Meaning in this document
AI / AO	Analog Input / Analog Output
AIC	Ampere interrupting capacity
DCU	Display Control Unit (Pfeiffer Vacuum display and control unit)
DI / DO	Digital Input / Digital Output
f	Rotation speed value of a vacuum pump (frequency, in rpm or Hz)
HPU	Handheld Programming Unit. Aid for control and monitoring pump parameters
I	Electric amperage
LED	Light emitting diode
[P:xxx]	Electronic drive unit control parameters. Printed in bold as a three-digit number in square brackets. Frequently displayed in conjunction with a short description Example: <b>[P:312]</b> software version
P	Electrical power
PE	Earthed conductor (protective earth)
R	Electrical resistance
RS-485	Standard for a physical interface for asynchronous serial data transmission (Recommended Standard)
t	Time
TC	Electronic drive unit (turbo controller)
TMS	Temperature management system
U	Electric voltage

Tbl. 2: Abbreviations used in this document





## 2 Safety

### 2.1 General safety instructions

This document includes the following 4 risk levels and 1 information level.

#### **DANGER**

##### **Imminent danger**

Indicates a hazardous situation which, if not avoided, will result in death or serious injury.

- ▶ Instructions on avoiding the hazardous situation

#### **WARNING**

##### **Possibly imminent danger**

Indicates a hazardous situation which, if not avoided, could result in death or serious injury.

- ▶ Instructions on avoiding the hazardous situation

#### **CAUTION**

##### **Possibly imminent danger**

Indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.

- ▶ Instructions on avoiding the hazardous situation

#### **NOTICE**

##### **Danger of property damage**

Notice is used to address practices not related to physical injury.

- ▶ Instructions on avoiding property damage



Notes, tips or examples indicate important information on the product or on this document.

### 2.2 Safety instructions

All safety instructions in this document are based on the results of the risk assessment carried out in accordance with Low Voltage Directive 2014/35/EU. Where applicable, all life cycle phases of the product were taken into account.

#### **Risks during installation**

#### **DANGER**

##### **Danger to life from electric shock**

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.



**⚠ DANGER**

**Danger to life from electric shock**

Power supply packs that are not specified or are not approved will lead to severe injury to death.

- ▶ Make sure that the power supply pack meets the requirements for double isolation between mains input voltage and output voltage, in accordance with IEC 61010 and IEC 60950.
- ▶ Make sure that the power supply pack meets the requirements in accordance with IEC 61010 and IEC 60950.
- ▶ Where possible, use original power supply packs or only power supply packs that correspond with the applicable safety regulations.

**⚠ WARNING**

**Danger to life from electric shock in the event of a fault**

In the event of a fault, devices connected to the mains may be live. There is a danger to life from electric shock when making contact with live components.

- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.

**⚠ WARNING**

**Risk of danger to life through missing mains disconnection device**

The vacuum pump and electronic drive unit are **not** equipped with a mains disconnection device (mains switch).

- ▶ Install a mains disconnection device according to SEMI-S2.
- ▶ Install a circuit breaker with an interruption rating of at least 10,000 A.

**⚠ WARNING**

**Risk of injury due to incorrect installation**

Dangerous situations may arise from unsafe or incorrect installation.

- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Ensure the integration into an Emergency Off safety circuit.

**Risks in the event of malfunctions**

**⚠ WARNING**

**Risk of injury from parts moving after a power failure or troubleshooting**

The "pumping station" function of the electronic drive unit will remain active after a power failure or if errors occur that shut down the vacuum pump or the system. When power is restored or after acknowledging a fault, the vacuum pump runs up automatically. There is a risk of injury to fingers and hands if they enter the operating range of rotating parts.

- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.
- ▶ Remove present mating plugs or bridges from the electronic drive unit possibly before the mains power returns, as these can cause an automatic run-up.
- ▶ Switch the pump off using the "Pumping station" function (parameter **[P:010]**).

## 2.3 Safety precautions



**Duty to provide information on potential dangers**

The product holder or user is obliged to make all operating personnel aware of dangers posed by this product.

Every person who is involved in the installation, operation or maintenance of the product must read, understand and adhere to the safety-related parts of this document.





#### Infringement of conformity due to modifications to the product

The Declaration of Conformity from the manufacturer is no longer valid if the operator changes the original product or installs additional equipment.

- Following the installation into a system, the operator is required to check and re-evaluate the conformity of the overall system in the context of the relevant European Directives, before commissioning that system.

#### General safety precautions when handling the product

- ▶ Before performing all work on the product, disconnect all installations connected to it safely from the mains voltage.
- ▶ Observe all applicable safety and accident prevention regulations.
- ▶ Check that all safety measures are observed at regular intervals.
- ▶ Recommendation: Establish a secure connection to the earthed conductor (PE); protection class I.
- ▶ Never disconnect plug connections during operation.
- ▶ Keep lines and cables away from hot surfaces ( $> 70\text{ °C}$ ).
- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Observe the unit protection class prior to installation or operation in other environments.
- ▶ Observe the protection class specified by ensuring the correct seating of the present sealing plugs.
- ▶ Disconnect the electronic drive unit only once everything has come to a complete standstill and when the mains power supply of the Turbopump is interrupted.

## 2.4 Limits of use of the product

Installation location	weatherproof (internal space)
Air pressure	750 hPa to 1060 hPa
Installation altitude	max. 2000 m
Rel. air humidity	max. 80%, at $T < 31\text{ °C}$ , up to max. 50% at $T < 40\text{ °C}$
Protection class	I
Excess voltage category	II
Permissible protection class	IP54
Degree of contamination	2
Ambient temperature	$+5\text{ °C}$ to $+40\text{ °C}$

**Tbl. 3: Permissible ambient conditions**



#### Notes on ambient conditions

The specified permissible ambient temperatures apply to operation of the turbopump at maximum permissible backing pressure or at maximum gas throughput, depending on the cooling type. The turbopump is intrinsically safe thanks to redundant temperature monitoring.

- The reduction in backing pressure or gas throughput permits operation of the turbopump at higher ambient temperatures.
- If the maximum permissible operating temperature of the turbopump is exceeded, the electronic drive unit first reduces the drive output and then switches it off where necessary.

## 2.5 Proper use

- The electronic drive unit is used exclusively for the operation of Pfeiffer Vacuum turbopumps and their accessories.



## 2.6 Foreseeable misuse

Improper use of the product invalidates all warranty and liability claims. Any use that is counter to the purpose of the product, whether intentional or unintentional, is regarded as misuse, in particular:

- Connection to the current supply that do not comply with the provisions of IEC 61010 or IEC 60950
- Operation with excessively high radiated heat output
- Use in areas with ionizing radiation
- Operation in explosion-hazard areas
- Use of accessories or spare parts that are not listed in these instructions



## 3 Product description

### 3.1 Identifying the product

- ▶ To ensure clear identification of the product when communicating with Pfeiffer Vacuum, always keep all of the information on the rating plate to hand.
- ▶ Learn about certifications through test seals on the product or at [www.certipedia.com](http://www.certipedia.com) with company ID no. 000021320.

### 3.2 Product features

The type TC 1200 electronic drive unit is a permanent component of the turbopump. The purpose of the electronic drive unit is to drive, monitor and control the entire turbopump.

Feature	TC 1200
Connection panel	Standard (RS-485)
Turbopump HiPace	1200, 1500, 1800, 2300, 2800
Mains power supply	100 to 120 / 200 to 240 V AC ( $\pm 10\%$ ) 50/60 Hz
Current draw max.	10 A
Max. power consumption	1350 VA
Internal fuse (mains connection)	10 A, slow blow
Interruption rating (AIC)	1500 A

Tbl. 4: Features of the device variant

Mains voltage $\pm 10\%$	Output of the electronic drive unit
100 to 120 V AC	700 to 930 W
200 to 240 V AC	1200 W

Tbl. 5: Drive power depending on the supplied mains voltage

### 3.3 Function

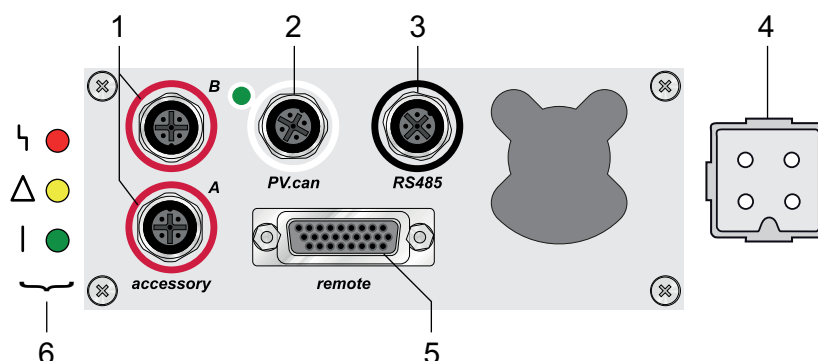


Fig. 1: TC 1200 connection panel

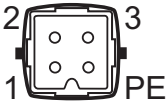




- |                               |                               |
|-------------------------------|-------------------------------|
| 1 Connection "accessory A+B"  | 4 Mains connection "AC in"    |
| 2 Service connection "PV.can" | 5 "remote" connection         |
| 3 Connection "RS485"          | 6 LEDs Operating mode display |

### 3.4 Scope of delivery

- TC 1200
- Operating instructions



### 3.5 Connections

Connection	Description
	<b>AC in</b> Housing plug HAN 3A for the voltage supply
	<b>accessory<sup>1)</sup></b> M12 socket with screw lock for the connection of Pfeiffer Vacuum accessories. The use of a Y-distributor permits the double allocation of a connection.
	<b>PV.can</b> M12 bushing with threaded coupling and LED for Pfeiffer Vacuum service purposes.
	<b>remote</b> High-density sub-D bushing with 26 pins for connection and configuration of a remote control.
	<b>RS-485</b> M12 socket with screw lock for the connection of Pfeiffer Vacuum control panels or PC. The use of a Y-distributor permits the integration into a bus system.

Tbl. 6: Connection description of the electronic drive unit

1) The "accessory" connection is described in the operating instructions of the Turbopump.



## 4 Installation

### 4.1 Connection diagram

#### DANGER

##### Danger to life from electric shock

Power supply packs that are not specified or are not approved will lead to severe injury to death.

- ▶ Make sure that the power supply pack meets the requirements for double isolation between mains input voltage and output voltage, in accordance with IEC 61010 and IEC 60950.
- ▶ Make sure that the power supply pack meets the requirements in accordance with IEC 61010 and IEC 60950.
- ▶ Where possible, use original power supply packs or only power supply packs that correspond with the applicable safety regulations.

#### DANGER

##### Danger to life from electric shock

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.

#### WARNING

##### Risk of injury due to incorrect installation

Dangerous situations may arise from unsafe or incorrect installation.

- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Ensure the integration into an Emergency Off safety circuit.



##### Contact load for the accessory connections to "accessory"

1. Maintain the maximum contact load of 200 mA per connection.
2. However, do not exceed the total sum of the load of all connections of 450 mA.



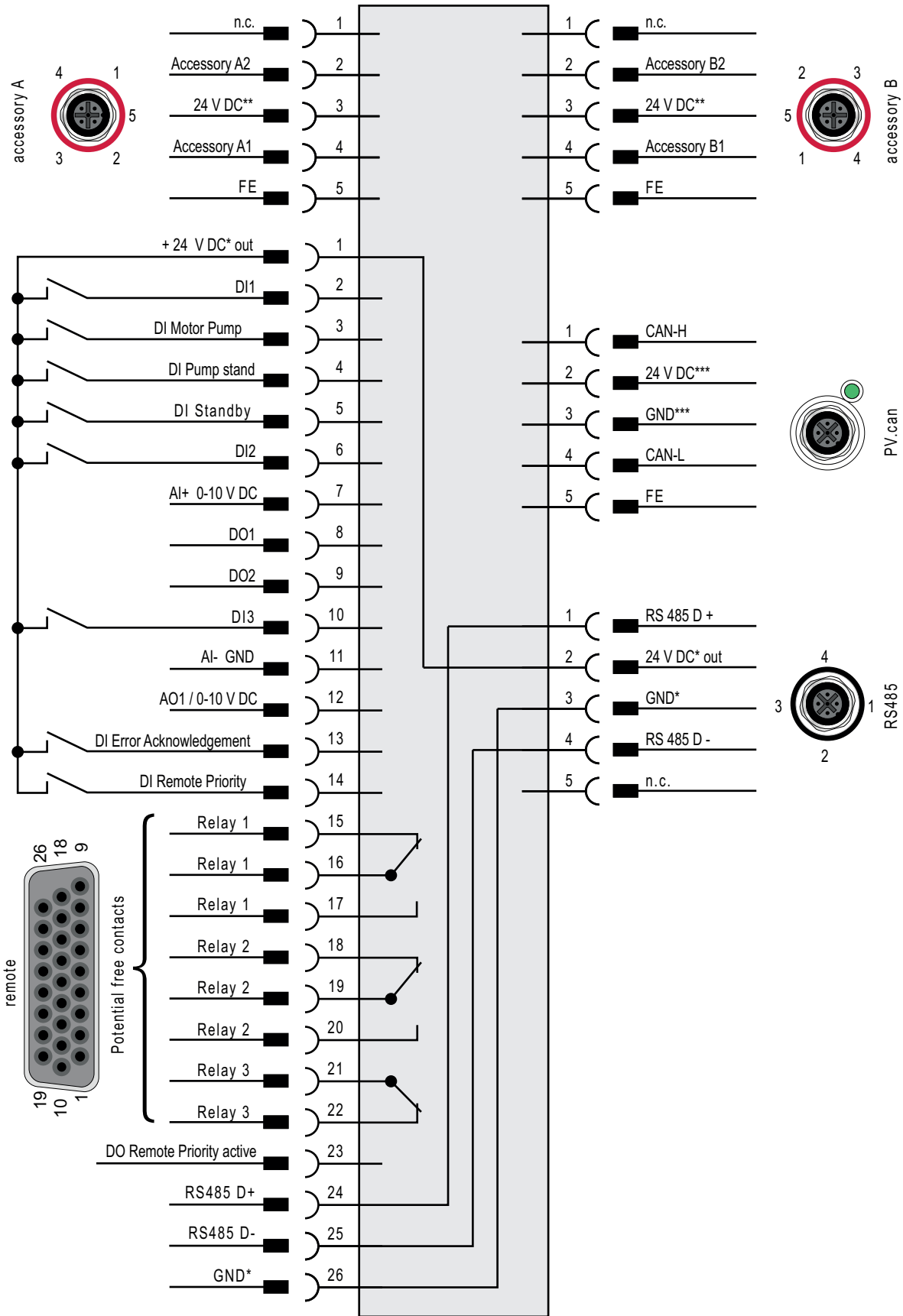


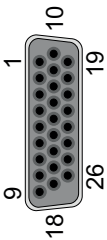
Fig. 2: Diagram and assignments of the connection panel





## 4.2 "remote" connection

The 26-pin sub-D connection with the "remote" designation offers the possibility to operate the electronic drive unit via remote control. The accessible individual functions are mapped to "PLC levels". The following specifications are the factory settings for the electronic drive unit. They can be configured with the Pfeiffer Vacuum parameter set.

	Pin	Function	Assignment <sup>2)</sup>
	1	+24 V DC* output (V+)	Reference voltage for all digital inputs and outputs
	2	DI1	Enable venting; open: off; V+: on
	3	DI motor pump	Drive motor; open: off; V+: on
	4	DI Pumping station	open: off; V+: on and malfunction acknowledgement
	5	DI Standby	Standby speed; open: off; V+: on
	6	DI2	Heater; open: off; V+: on
	7	AI+ speed-control operation	Setpoint in speed-control operation 2 to 10 V DC corresponds to 20 to 100% of the nominal rotation speed
	8	DO1	Speed-control switch point reached GND: no, V+: yes ( $I_{max} = 50 \text{ mA}/24 \text{ V}$ )
	9	DO2	GND: Fault; V+: no fault ( $I_{max} = 50 \text{ mA}/24 \text{ V}$ )
	10	DI3	Sealing gas; open: off; V+: on
	11	AI rotation speed setting operation GND	Setpoint in rotation speed setting operation; GND
	12	AO1	Actual speed; 0 to 10 V DC corresponds to 0 to 100% $R_L > 10 \text{ k}\Omega$
	13	DI malfunction acknowledgement	Malfunction acknowledgement: V+ pulse (min. 500 ms)
	14	DI Remote priority	Operation via "remote" interface; open: off; V+: set and takes priority over other digital inputs
	15	Relay 1	Connection with pin 16, if relay 1 inactive
	16		Rotation speed switchpoint reached; relay contact 1 ( $\text{rpm}_{max} = 50 \text{ V DC}$ ; $I_{max} = 1 \text{ A}$ )
	17		Connection with pin 16, if relay 1 active
	18	Relay 2	Connection with pin 19, if relay 2 inactive
	19		No fault; relay contact 2 ( $\text{rpm}_{max} = 50 \text{ V DC}$ ; $I_{max} = 1 \text{ A}$ )
	20		Connection with pin 19, if relay 2 active
	21	Relay 3	Connection with pin 22, if relay 3 inactive
	22		Warning; relay contact 3 ( $\text{rpm}_{max} = 50 \text{ V DC}$ ; $I_{max} = 1 \text{ A}$ )
	23	DO remote priority	GND: off; V+: Remote priority active
	24	RS-485 D+	in accordance with the specification and Pfeiffer Vacuum protocol
	25	RS-485 D-	
	26	Ground (GND)	Reference earth for all digital inputs and outputs

Tbl. 7: Terminal lay-out of 26-pin "remote" connection

### Establish remote connection


1. Remove the remote plug from the electronic drive unit and connect a remote control.
2. Utilize a screened plug and cable.

2) Factory setting



### 4.3 Connection "RS-485"

The interface with the designation "RS-485" on the electronic drive unit is intended for the connection of a Pfeiffer Vacuum display and control panel (DCU or HPU) or an external computer. The connections are galvanically safe and are isolated from the maximum supply voltage for the electronic drive unit. The electrical connections are optically decoupled internally.

	Pin	Assignment
	1	RS-485 D+
	2	+24 V output, ≤ 210 mA loading capacity
	3	GND
	4	RS-485 D-
	5	not connected

Tbl. 8: Terminal layout of the RS-485 connecting socket M12

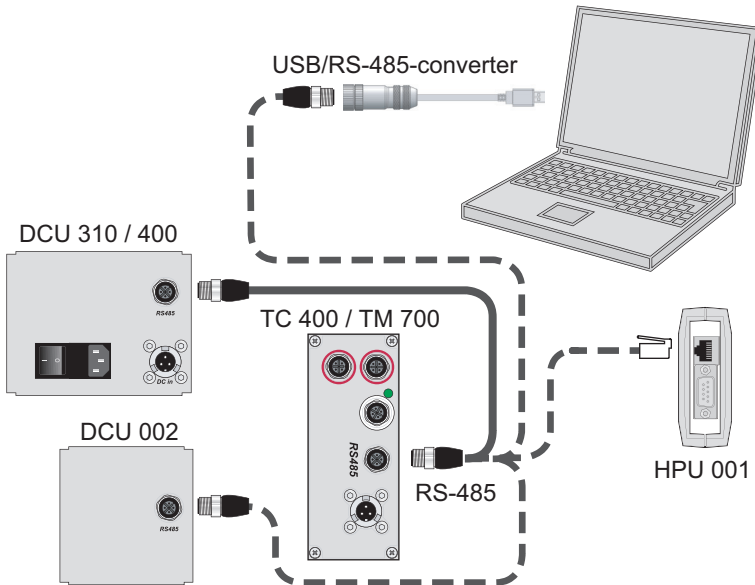


Fig. 3: Connecting RS-485 devices

#### Connecting RS-485 devices

At interface RS-485, one external control panel can be connected in each case.

1. Use the respective connection cable supplied with the control panel or from the range of accessories.
2. Use the option to connect a PC via the USB/RS-485 converter.

### 4.4 Mains power supply

**⚠ WARNING**

**Risk of injury due to incorrect installation**

Dangerous situations may arise from unsafe or incorrect installation.

- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Ensure the integration into an Emergency Off safety circuit.

**⚠ WARNING**

**Danger to life from electric shock in the event of a fault**

In the event of a fault, devices connected to the mains may be live. There is a danger to life from electric shock when making contact with live components.


- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.



**⚠ WARNING****Risk of danger to life through missing mains disconnection device**

The vacuum pump and electronic drive unit are **not** equipped with a mains disconnection device (mains switch).

- ▶ Install a mains disconnection device according to SEMI-S2.
- ▶ Install a circuit breaker with an interruption rating of at least 10,000 A.

	Pin	Assignment
	1	Phase L
	2	Neutral conductor
	3	not connected
	PE	Earthed conductor

**Tbl. 9: Terminal lay-out of the power supply connector**

**Establishing mains connection**

1. Order a corresponding power supply cable from the Pfeiffer Vacuum accessories range.
2. Assemble your own power supply cable using the HAN 3A connecting socket from the shipment.
3. Plug mains cable into the mains connection "AC in".
4. Secure the mains cable using a mounting bracket.
5. Connect the mains cable to the mains.



## 5 Interfaces

### 5.1 Interface RS-485

**⚠ DANGER**

**Danger to life from electric shock**


When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.

The interface with the designation "RS-485" on the electronic drive unit is intended for the connection of a Pfeiffer Vacuum display and control panel (DCU or HPU) or an external computer. The connections are galvanically safe and are isolated from the maximum supply voltage for the electronic drive unit. The electrical connections are optically decoupled internally.

Designation	Value
Serial interface	RS-485
Baudrate	9600 Baud
Data word length	8 bit
Parity	none (no parity)
Start bits	1
Stop bits	1

**Tbl. 10: Features of the RS-485 interface**

	Pin	Assignment
	1	RS-485 D+
	2	+24 V output, ≤ 210 mA loading capacity
	3	GND
	4	RS-485 D-
	5	not connected

**Tbl. 11: Terminal layout of the RS-485 connecting socket M12**



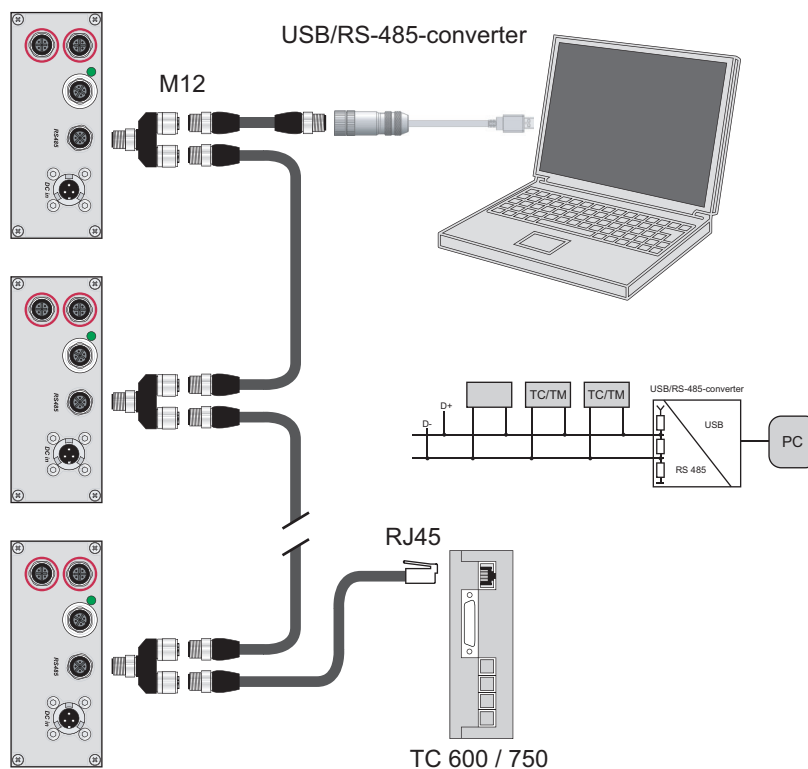


Fig. 4: Networking of several electronic drive units in RS-485 Bus

### Networking as RS-485 Bus

The group address of the electronic drive unit is 963.

1. Install the devices according to the specification for RS-485 interfaces.
2. Make sure that all devices connected to the bus have different RS-485 device addresses [P:797].
3. Connect all devices to the bus with RS-485 D+ and RS-485 D-.

## 5.2 Pfeiffer Vacuum protocol for RS-485 interface

### 5.2.1 Telegram frame

The telegram frame of the Pfeiffer Vacuum protocol contains only ASCII code characters [32; 127], the exception being the end character of the telegram  $C_R$ . Basically, a master (e.g. a PC) sends a telegram, which is answered by a slave (e.g. electronic drive unit or transmitter).

a2	a1	a0	*	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	$C_R$
a2 – a0		Unit address for slave														
		<ul style="list-style-type: none"> <li>• Individual address of the unit ["001";"255"]</li> <li>• Group address "9xx" for all identical units (no response)</li> <li>• global address "000" for all units on the bus (no response)</li> </ul>														
*		Action according to telegram description														
n2 – n0		Pfeiffer Vacuum parameter numbers														
l1 – l0		Data length dn to d0														
dn – d0		Data in the respective data type (see chapter "Data types", page 22).														
c2 – c0		Checksum (sum of ASCII values of cells a2 to d0) modulo 256														
$C_R$		carriage return (ASCII 13)														

### 5.2.2 Telegram description

Data query --> ?

a2	a1	a0	0	0	n2	n1	n0	0	2	=	?	c2	c1	c0	$C_R$
----	----	----	---	---	----	----	----	---	---	---	---	----	----	----	-------



**Control command**  -->  !

a2	a1	a0	1	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	C <sub>R</sub>
----	----	----	---	---	----	----	----	----	----	----	-----	----	----	----	----	----------------

**Data response / Control command understood**  --> 

a2	a1	a0	1	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	C <sub>R</sub>
----	----	----	---	---	----	----	----	----	----	----	-----	----	----	----	----	----------------

**Error message**  --> 



a2	a1	a0	1	0	n2	n1	n0	0	6	N	O	_	D	E	F	c2	c1	c0	C <sub>R</sub>
										_	R	A	N	G	E				
										_	L	O	G	I	C				

- NO\_DEF            Parameter number n2–n0 no longer exists
- \_RANGE          Data dn–d0 outside the permissible range
- \_LOGIC          Logical access error

### 5.2.3 Telegram example 1



**Data query**

Current rotation speed (parameter **[P:309]**, device address slave: "123")

 -->  ?	1	2	3	0	0	3	0	9	0	2	=	?	1	1	2	C <sub>R</sub>
ASCII	49	50	51	48	48	51	48	57	48	50	61	63	49	49	50	13

**Data response: 633 Hz**



Current rotation speed (parameter **[P:309]**, device address Slave: "123")

 --> 	1	2	3	1	0	3	0	9	0	6	0	0	6	3	3	0	3	7	C <sub>R</sub>	
ASCII	49	50	51	49	48	51	48	57	48	54	48	48	48	54	51	51	48	51	55	13

### 5.2.4 Telegram example 2



**Control command**

Switch on the pumping station (parameter **[P:010]**, device address Slave: "042")

 -->  !	0	4	2	1	0	0	1	0	0	6	1	1	1	1	1	1	0	2	0	C <sub>R</sub>
ASCII	48	52	50	49	48	48	49	48	48	54	49	49	49	49	49	49	48	50	48	13

**Control command understood**

Switch on the pumping station (parameter **[P:010]**, device address Slave: "042")

 --> 	0	4	2	1	0	0	1	0	0	6	1	1	1	1	1	1	0	2	0	C <sub>R</sub>
ASCII	48	52	50	49	48	48	49	48	48	54	49	49	49	49	49	49	48	50	48	13

### 5.2.5 Data types

No.	Data type	Description	Length l1 – l0	Example
0	boolean_old	Logical value (false/true)	06	000000 corresponds with false 111111 corresponds with true
1	u_integer	Positive whole number	06	000000 to 999999
2	u_real	Positive fixed point number	06	001571 corresponds with 15.71



No.	Data type	Description	Length I1 – I0	Example
3	u_expo	Positive exponential number	06	1.2E-2 corresponds with $1,2 \cdot 10^{-2}$ 005E8 corresponds with $5 \cdot 10^8$
4	string	Any character string with 6 characters. ASCII codes between 32 and 127	06	TC_110, TM_700
6	boolean_new	Logical value (false/true)	01	0 corresponds with false 1 corresponds with true
7	u_short_int	Positive whole number	03	000 to 999
10	u_expo_new	Positive exponential number. The last of both digits are the exponent with a deduction of 20.	06	100023 corresponds with $1,0 \cdot 10^3$ 100000 corresponds with $1,0 \cdot 10^{-20}$
11	string16	Any character string with 16 characters. ASCII codes between 32 and 127	16	this-is-an-example
12	string8	Any character string with 8 characters. ASCII codes between 32 and 127	08	Example



## 6 Parameter set

### 6.1 General


Important settings and function-related characteristics are factory-programmed into the electronic drive unit as parameters. Each parameter has a three-digit number and a description. The use of the parameter is possible via Pfeiffer Vacuum displays and control panels, or externally via RS-485 using Pfeiffer Vacuum protocol.

The vacuum pump starts in standard mode with factory default pre-set parameters.




#### Non-volatile data storage

When switching off or in the event of unintentional voltage drop, the **parameters** and the operating hours stay saved in the electronics.

#	Three digit number of the parameter
Display	Display of parameter description
Description	Brief description of the parameters
Functions	Function description of the parameters
Data type	Type of formatting of the parameter for the use with the Pfeiffer Vacuum protocol
Access type	R (read): Read access; W (write): Write access
Unit	Physical unit of the described variable
min. / max.	Permissible limit values for the entry of a value
default	Factory default pre-setting (partially pump-specific)
	The parameter can be saved non-volatile in the electronic drive unit










Tbl. 12: Explanation and meaning of the parameters

### 6.2 Control commands

#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	default	
001	Heating	Heating	0 = off 1 = on	0	RW		0	1	0	✓
002	Standby	Standby	0 = off 1 = on	0	RW		0	1	0	✓
004	RUTimeCtrl	Run-up time monitoring	0 = off 1 = on	0	RW		0	1	1	✓
009	ErrorAckn	Malfunction acknowledgement	1 = Malfunction acknowledgement	0	W		1	1		
010	PumpgStatn	Pumping station	0 = off 1 = on and malfunction acknowledgement	0	RW		0	1	0	✓
012	EnableVent	Enable vents	0 = no 1 = yes	0	RW		0	1	0	✓
013	Brake	Brake	0 = off 1 = on	0	RW		0	1	0	✓
017	CfgSpdSwPt	Rotation speed switch point configuration	0 = Rotation speed switch point 1 1 = Rotation speed switch points 1 & 2	7	RW		0	1	0	✓























#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	de- fault	
019	Cfg DO2	Configuration output DO2	0 = Rotation speed switch point reached 1 = No error 2 = Error 3 = Warning 4 = Error and/or warning 5 = Set rotation speed reached 6 = Pump on 7 = Pump accelerating 8 = Pump decelerating 9 = Always "0" 10 = Always "1" 11 = Remote priority active 12 = Heater 13 = Backing pump 14 = Sealing gas 15 = Pumping station 16 = Pump rotating 17 = Pump has stopped 18 = TMS steady state 19 = Pressure switch point 1 not reached 20 = Pressure switch point 2 not reached 21 = Fore-vacuum valve is decelerating 22 = Backing pump stand-by	7	RW		0	22	1	
023	MotorPump	Motor pump	0 = off 1 = on	0	RW		0	1	0	
024	Cfg DO1	Configuration output DO1	Settings, see <b>[P:019]</b>	7	RW		0	22	0	
025	OpMode BKP	Backup pump operating mode	0 = continuous operation 1 = intermittent operation 2 = Delayed switching on	7	RW		0	2	0	
026	SpdSetMode	Speed actuator operation	0 = off 1 = on	7	RW		0	1	0	
027	GasMode	Gas mode	0 = heavy gases 1 = light gases 2 = Helium	7	RW		0	2	0	
028	Cfg Remote	Remote configuration	0 = Standard 4 = Relay, inverted	7	RW		0	4	0	
030	VentMode	Vent mode	0 = delayed venting 1 = do not vent 2 = vent directly	7	RW		0	2	0	



Parameter set



#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	de- fault	
035	Cfg Acc A1	Configuration accessory connection A1	0 = fan 1 = Venting valve, closed without current 2 = Heater 3 = Backing pump 4 = Fan (temperature controlled) 5 = Sealing gas 6 = Always "0" 7 = Always "1" 8 = Power failure venting unit 9 = TMS Heater 10 = TMS Cooling 12 = Second venting valve 13 = Sealing gas monitoring 14 = Heating (lower part temperature controlled)	7	RW		0	14	5	
036	Cfg Acc B1	Configuration accessory connection B1	Options, see <b>[P:035]</b>	7	RW		0	14	1	
037	Cfg Acc A2	Configuration accessory connection A2	Options, see <b>[P:035]</b>	7	RW		0	14	3	
038	Cfg Acc B2	Configuration accessory connection B2	Options, see <b>[P:035]</b>	7	RW		0	14	2	
041	Press1HVen	Release HV sensor integrated (only IKT)	0 = off 1 = on 2 = On, with rotation speed switch point reached 3 = On, with pressure switch point not reached	7	RW		0	3	2	
045	Cfg Rel R1	Configuration, relay 1	Options, see <b>[P:019]</b>	7	RW		0	22	0	
046	Cfg Rel R2	Configuration, relay 2	Options, see <b>[P:019]</b>	7	RW		0	22	1	
047	Cfg Rel R3	Configuration, relay 3	Options, see <b>[P:019]</b>	7	RW		0	22	3	
050	SealingGas	Sealing gas	0 = off 1 = on	0	RW		0	1	0	
055	Cfg AO1	Configuration output AO1	0 = actual speed 1 = output 2 = current 3 = Always 0 V 4 = Always 10 V 5 = Follows AI1 6 = Pressure value 1 7 = Pressure value 2 8 = Fore-vacuum control	7	RW		0	8	0	
057	Cfg AI1	Configuration input AI1	0 = Switched off 1 = Setpoint in speed-control operation	7	RW		0	1	0	



#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	de- fault	
060	CtrlVialnt	Operation of the interface	1 = remote 2 = RS-485 4 = PV.can 8 = Fieldbus 16 = E74 255 = Unlock interface selection	7	RW		0	255	2	
061	IntSelLckd	Interface selection locked	0 = off 1 = on	0	RW		0	1	0	
062	Cfg DI1	Configuration input DI1	Setting ≠ [P:063/064] 0 = Deactivated 1 = Enable vents 2 = Heater 3 = Sealing gas 4 = Run-up time monitoring 5 = Rotation speed mode 7 = Enable HV sensor	7	RW		0	7	1	
063	Cfg DI2	Configuration input DI2	Options, see [P:062] Setting ≠ [P:062/064]	7	RW		0	7	2	
064	Cfg DI3	Configuration input DI3	Options, see [P:062] Setting ≠ [P:062/063]	7	RW		0	7	3	

Tbl. 13: Control commands

### 6.3 Status requests


#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	de- fault	
300	RemotePrio	Remote priority	0 = no 1 = yes	0	R		0	1		
301	OpFluidDef	Operating fluid low	0 = no 1 = yes	0	R		0	1		
302	SpdSwPtAtt	Speed-control switch point reached	0 = no 1 = yes	0	R		0	1		
303	Error code	Error code		4	R					
304	OvTempElec	Excess temperature drive electronics	0 = no 1 = yes	0	R		0	1		
305	OvTempPump	Excess temperature pump	0 = no 1 = yes	0	R		0	1		
306	SetSpdAtt	Target speed reached	0 = no 1 = yes	0	R		0	1		
307	PumpAccel	Pump accelerating	0 = no 1 = yes	0	R		0	1		
308	SetRotSpd	Set rotation speed (Hz)		1	R	Hz	0	999999		
309	ActualSpd	Actual rotational speed (Hz)		1	R	Hz	0	999999		
310	DrvCurrent	Drive current		2	R	A	0	9999.99		
311	OpHrsPump	Pump operating hours		1	R	h	0	65535		
312	Fw version	Drive electronics software version		4	R					
313	DrvVoltage	Drive voltage		2	R	V	0	9999.99		




















#	Display	Designations	Func-tions	Data type	Access type	Unit	min.	max.	de-fault	
314	OpHrsElec	Drive electronics operating hours		1	R	h	0	65535		✓
315	Nominal Spd	Nominal rotation speed (Hz)		1	R	Hz	0	999999		
316	DrvPower	Drive power		1	R	W	0	999999		
319	PumpCycles	Pump cycles		1	R		0	65535		✓
324	TempPwrStg	Final stage temperature		1	R	°C	0	999999		
326	TempElec	Electronics temperature		1	R	°C	0	999999		
330	TempPmpBot	Pump lower part temperature		1	R	°C	0	999999		
331	TMSactTemp	Current TMS heating temperature		1	R	°C	0	999999		
333	TMS steady	TMS steady state temperature	0 = no 1 = yes	0	R		0	1		
336	AccelDecel	Acceleration/deceleration		1	R	rpm/s	0	999999		
337	SealGasFlw	Sealing gas flow		1	R	sccm	0	999999		
342	TempBearng	Bearing temperature		1	R	°C	0	999999		
346	TempMotor	Motor temperature		1	R	°C	0	999999		
349	ElecName	Electronic drive unit designation		4	R					
354	HW Version	Hardware version drive electronics		4	R					
360	ErrHist1	Error code history, item 1		4	R					✓
361	ErrHist2	Error code history, item 2		4	R					✓
362	ErrHist3	Error code history, item 3		4	R					✓
363	ErrHist4	Error code history, item 4		4	R					✓
364	ErrHist5	Error code history, item 5		4	R					✓
365	ErrHist6	Error code history, item 6		4	R					✓
366	ErrHist7	Error code history, item 7		4	R					✓
367	ErrHist8	Error code history, item 8		4	R					✓
368	ErrHist9	Error code history, item 9		4	R					✓
369	ErrHist10	Error code history, item 10		4	R					✓
384	TempRotor	Rotor temperature		1	R	°C	0	999999		
397	SetRotSpd	Set rotation speed (rpm)		1	R	rpm	0	999999		
398	ActualSpd	Actual speed (rpm)		1	R	rpm	0	999999		
399	NominalSpd	Nominal rotation speed (rpm)		1	R	rpm	0	999999		

Tbl. 14: Status requests

## 6.4 Set value settings

#	Display	Designations	Func-tions	Data type	Access type	Unit	min.	max.	default	
700	RUtimeSVal	Set value run-up time		1	RW	min	1	120	8	✓
701	SpdSwPt1	Rotation speed switch point 1		1	RW	%	50	97	80	✓
704	TMSsetTemp	TMS heating temperature specification		1	RW	°C	30	75	40	✓
707	SpdSVal	Setpoint in speed-control operation		2	RW	%	20	100	65	✓



#	Display	Designations	Functions	Data type	Access type	Unit	min.	max.	default	
708	PwrSVal	Set value power consumption		7	RW	%	10	100	100 <sup>3)</sup>	
710	Swoff BKP	Backup pump switch-off threshold for intermittent operation		1	RW	W	0	1000	0	
711	SwOn BKP	Backup pump switch-on threshold for intermittent operation		1	RW	W	0	1000	0	
717	StdbySVal	Rotational speed setpoint in standby operation		2	RW	%	20	100	66.7	
719	SpdSwPt2	Rotation speed switch point 2		1	RW	%	5	97	20	
720	VentSpd	Venting at rotation speed, delayed venting		7	RW	%	40	98	50	
721	VentTime	Venting time, delayed venting		1	RW	s	6	3600	3600	
730	PrsSwPt 1	Pressure switch point 1		10	RW	hPa				
732	PrsSwPt 2	Pressure switch point 2		10	RW	hPa				
739	PrsSn1Name	Name sensor 1		4	R					
740	Pressure 1	Pressure value 1		10	RW	hPa				
742	PrsCorrPi 1	Correction factor 1		2	RW					
749	PrsSn2Name	Name sensor 2		4	R					
750	Pressure 2	Pressure value 2		10	RW	hPa				
752	PrsCorrPi 2	Correction factor 2		2	RW					
777	NomSpdConf	Confirmation of nominal rotational speed		1	RW	Hz	0	1500	0	
791	SlgWrnThrs	Sealing gas flow warning threshold		1	RW	sccm	5	200	15	
797	RS485Adr	RS-485 Interface address		1	RW		1	255	1	

Tbl. 15: Set value settings


## 6.5 Additional parameter for the DCU



### Additional parameter in the control panel

The basic parameter set is set in the electronic drive unit ex-factory. For controlling connected external components (e.g. vacuum measuring instruments), additional parameters (extended parameter set) are available in the corresponding Pfeiffer Vacuum display and control panels.


- Refer to the corresponding operating instructions of the respective components.
- Select the extended parameter set with parameter **[P:794] = 1**.

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	de-fault	
340	Pressure	Actual pressure value (ActiveLine)		7	R	hPa	$1 \cdot 10^{-10}$	$1 \cdot 10^3$		
350	Ctr Name	Display and control panel: type		4	R					
351	Ctr Software	Display and control panel: software version		4	R					
738	Gauge type	Type of pressure gauge		4	RW					

3) Depending on the pump type



Parameter set

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	de- fault	
794	Param set	Parameter set	0 = Basic parameter set 1 = Extended parameter set	7	RW		0	1	0	
795	Servicelin	Insert service line		7	RW				795	

Tbl. 16: Parameter for DCU functions



## 7 Operation

### 7.1 Configuring the connections with the Pfeiffer Vacuum parameter set

The electronic drive unit is pre-configured with the factory default basic functions and is ready for operation. For individual requirements, you can configure most connections for the electronic drive unit with the parameter set.

#### 7.1.1 Configuring the "remote" connection

In the description, "active" signifies:

- for all digital outputs: V+ active high
- for all relays: contact changeover in accordance with the settings **[P:028]**

Option	Description
0 = Speed-control switch point reached	active, once the switch-point is reached
1 = No error	active, with trouble-free operation
2 = Error	active, if the error message is active
3 = Warning	active, if a warning message is active
4 = Error and/or warning	active, if an error and/or warning is active
5 = Set rotation speed reached	active, once the set rotation speed switch-point is reached
6 = Pump on	active, if pumping station on, motor on and no error
7 = Pump accelerating	active, if pumping station on, current rotation speed < set rotation speed
8 = Pump decelerating	active, if pumping station on, current rotation speed > set rotation speed pumping station off, rotation speed > 3 Hz
9 = always 0	GND for the control of an external device
10 = always 1	+24 V DC for the control of an external device
11 = Remote priority active	active, if the remote priority is active
12 = Heater	Control corresponds to parameter <b>[P:001]</b>
13 = Backing pump	Control corresponds to parameter <b>[P:010]</b> and <b>[P:025]</b>
14 = Sealing gas	Control corresponds to parameter <b>[P:050]</b>
15 = Pumping station	Control corresponds to parameter <b>[P:010]</b>
16 = Pump rotating	active, if rotation speed > 1 Hz
17 = Pump has stopped	active, if rotation speed < 2 Hz
18 = TMS steady state <sup>4)</sup>	active, if TMS set temperature stabilized
19 = Pressure switch point 1 not reached	Control corresponds to parameter <b>[P:730]</b> ( <b>[P:740]</b> < <b>[P:730]</b> )
20 = Pressure switch point 2 not reached	Control corresponds to parameter <b>[P:732]</b> ( <b>[P:750]</b> < <b>[P:732]</b> )
21 = Fore-vacuum valve is decelerating	+24 V DC time-delayed after pumping station on
22 = Backing pump stand-by	Control of backing pump stand-by mode

Tbl. 17: Digital outputs and relays

Option	Description
0 = Deactivated	Connection not operational
1 = Enable vents	Control corresponds to parameter <b>[P:012]</b>
2 = Heater	Control corresponds to parameter <b>[P:001]</b>
3 = Sealing gas	Control corresponds to parameter <b>[P:050]</b>

4) Only when using pumps with a temperature management system (TMS)



Option	Description
4 = Run-up time monitoring	Control corresponds to parameter <b>[P:004]</b>
5 = Rotation speed mode	Control corresponds to parameter <b>[P:026]</b>
7 = Enable HV sensor	Control corresponds to parameter <b>[P:041]</b> (0 or 1 only)

**Tbl. 18: Digital inputs**

Option	Description
0 = actual speed	Rotation speed signal; $0 - 10 \text{ VDC} = 0 - 100\% \times f_{\text{nominal}}$
1 = output	Output signal; $0 - 10 \text{ VDC} = 0 - 100\% \times P_{\text{max}}$
2 = current	Current signal; $0 - 10 \text{ VDC} = 0 - 100\% \times I_{\text{max}}$
3 = Always 0 V	Always GND
4 = Always 10 V	Output of permanent 10 V DC
5 = Follows AI1	Follows analog input 1
6 = Pressure value 1	Pressure value signal 0 V: Error 1 V: Not reached $1.5 - 8.5 \text{ V for sensor RPT } p \text{ (hPa)} = 10^{(U-5.5 \text{ V})}$ $1.5 - 8.5 \text{ V for sensor IKT } p \text{ (hPa)} = 10^{(U-10.5 \text{ V})}$ 9 V: Exceed
7 = Pressure value 2	
8 = Fore-vacuum control	

**Tbl. 19: Analog output**

Option	Description
0 = Switched off	Connection not operational
1 = Setpoint in speed-control operation	Rotation speed setting operation via pin 7 (0 – 10 V) and pin 11 (GND)

**Tbl. 20: Analog input**

**Procedure**

1. Set the digital outputs and relays via the parameters **[P:019]** and **[P:024]**, or **[P:045]**, **[P:046]**, **[P:047]** and **[P:028]**.
2. Set the digital inputs via the parameters **[P:062]**, **[P:063]** or **[P:064]**.
3. Set the analog output via parameter **[P:055]**.
4. Set the analog input via parameter **[P:057]**.

### 7.1.2 Configuring the accessory connections

Option	Description
0 = Fan	Control via pumping station parameters
1 = Venting valve, closed without current	Control via parameter Enable venting. When using a venting valve closed without current
2 = Heater	Control via heating and speed switch point reached parameters
3 = Backing pump	Control via parameter Pumping station and backing pump operating mode
4 = Fan (temperature controlled)	Control via parameter Pumping station and temperature threshold value
5 = Sealing gas	Control via parameter Pumping station and sealing gas
6 = Always "0"	GND for the control of an external device
7 = Always "1"	+24 V DC for the control of an external device
8 = Power failure venting unit	Control via parameter Enable venting. When using a power failure venting unit
9 = TMS Heater <sup>5)</sup>	Control via TMS switchbox





Option	Description
10 = TMS Cooling <sup>6)</sup>	Control of the cooling water supply TMS
13 = Sealing gas monitoring	Control via parameter Pumping station and sealing gas
14 = Heating (lower part temperature controlled)	Control of the heating. Control via lower part heating parameters

**Tbl. 21: Accessory connections**

#### Procedure

- ▶ Set the connections via parameter [P:035], [P:036], [P:037], or [P:038].

### 7.1.3 Select interfaces

The option "Control via Interface" serves the display of the interface currently active in the electronic drive unit. The communication interfaces thus automatically achieve control priority.

Option	Description
1 = remote	Operation via connection "remote"
2 = RS-485	Operation via connection "RS-485"
4 = PV.can	For service purposes only
8 = Fieldbus	Operation via fieldbus
16 = E74	Operation via connection "E74"

**Tbl. 22: Parameter [P:060]**

## 7.2 Operating modes

### 7.2.1 Gas type-dependent operation

#### NOTICE

##### Turbopump destruction due to gases with too high molecular masses

The pumping of gases with impermissible high molecular masses leads to the destruction of the turbopump.

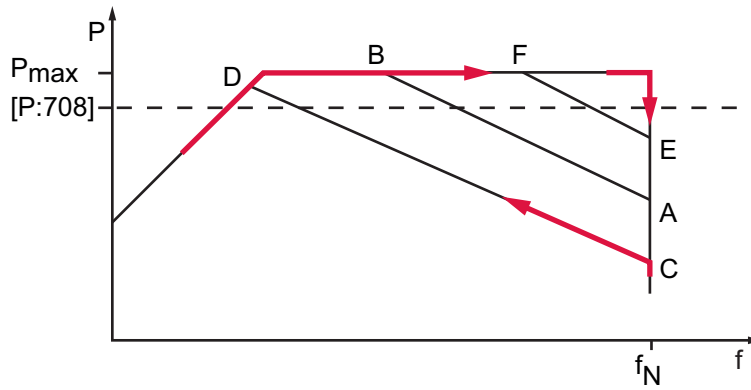
- ▶ Make sure that the gas mode is set correctly by [P:027] in the electronic drive unit.
- ▶ Consult Pfeiffer Vacuum before you use gases with higher molecular masses (> 80).

High gas throughput and high rotation speed lead to strong friction heating of the rotor. To avoid overheating, power to rotation speed characteristics are implemented in the electronic drive unit. The power characteristic enables the operation of the turbopump at any rotation speed with the maximum permissible gas throughput without thermally overloading the turbopump. The maximum power consumption depends on the gas type. 3 characteristics are available for the parameterization in order to completely exhaust the turbopump's capacity for each gas type.

5) Only for vacuum pumps with a temperature management system (TMS)

6) Only for vacuum pumps with a temperature management system (TMS)





**Fig. 5: Schematic diagram of power characteristics, example of heavy gases [P:027] = 0**

P	Power consumption	C-D	Power characteristic in gas mode "0" (gases with molecular mass > 39, e.g. Argon)
f	Rotation speed	A-B	Power characteristic in gas mode "1" (gases with molecular mass ≤ 39)
P <sub>max</sub>	Maximum power consumption	E-F	Power characteristic in gas mode "2" (Helium)
f <sub>N</sub>	Nominal rotation speed		

**Setting the gas mode**

1. Check the current gas mode set with parameter [P:027].
2. Set the parameter [P:027] to the required value.
3. If necessary, set a lower frequency in rotation speed setting mode in order to avoid rotation speed fluctuations.

The turbopump runs up with maximum power consumption. When the nominal respective set rotation speed is reached, the electronic drive unit automatically switches over to the chosen power characteristic of the selected gas mode. An increase in the power consumption initially compensates an increasing gas throughput to keep the rotation speed constant. However, the turbopump heats up higher due to increasing gas friction. When the gas-type-dependent maximum power is exceeded, the electronic drive reduces the rotation speed until a permissible balance between power and gas friction is achieved.

**7.2.2 Set value power consumption**

**Set parameter [P:708]**

When setting the specified power consumption below 100%, the run-up time is extended.

1. Set the parameter [P:708] to the required value in %.
2. Where necessary, adjust the parameter [P:700] RUTimeSVal to avoid error messages when starting up.

**7.2.3 Run-up time**

The turbopump run-up is time-monitored ex-factory. There are various causes of prolonged run-up times, for example:

- Excessive gas throughput
- Leak in system
- Setpoint of the run-up time too low

**Set parameter [P:700]**

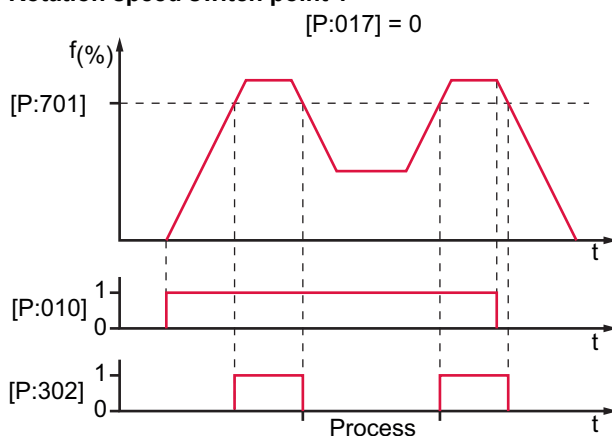
1. Where applicable, eliminate any external and application-related causes.
2. Adjust the run-up time with parameter [P:700].

**7.2.4 Rotation speed switch points**

You can use the rotation speed switch point for the "turbopump operational for the process" message. Exceeding or underrunning the active rotation speed switch point activates or deactivates a signal at the pre-configured output on the electronic drive unit and at the status parameter [P:302].



### Rotation speed switch point 1



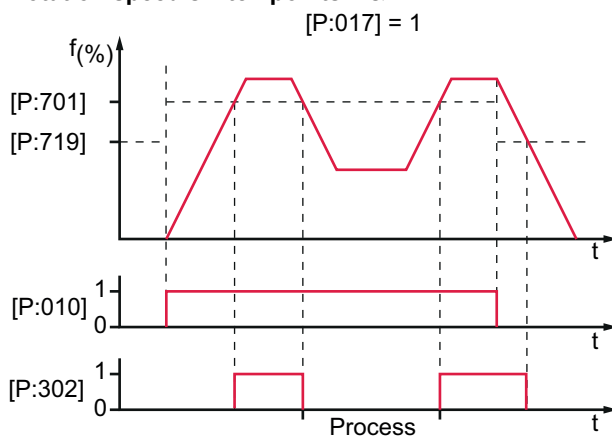
**Fig. 6: Rotation speed switch point 1 active**

### Adjusting rotation speed switch point 1

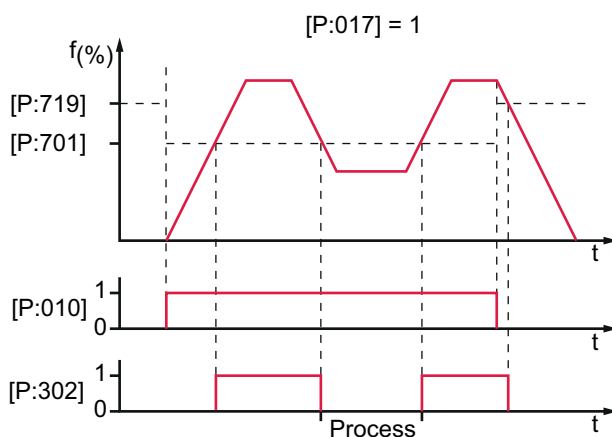
Signal output and status parameters are based on the set value for the rotation speed switch point 1 [P:701].

1. Set the parameter [P:701] to the required value in %.
2. Set the parameter [P:017] to "0".

### Rotation speed switch points 1 & 2



**Fig. 7: Rotation speed switch points 1 & 2 active, [P:701] > [P:719]**



**Fig. 8: Rotation speed switch points 1 & 2 active, [P:701] < [P:719]**



### Setting the rotation speed switch points 1 & 2

1. Set the parameter **[P:701]** to the required value in %.
2. Set the parameter **[P:719]** to the required value in %.
3. Set the parameter **[P:017]** to "1".

When the pumping station **[P:010]** is switched on, rotation speed switch point 1 is the signal generator. When the pumping station is switched off, the signal output and status request orientate at rotation speed switch point 2. The signal output is subject to the hysteresis between both switchpoints.

## 7.2.5 Rotation speed setting mode

The rotation speed setting mode reduces the speed and hence the pumping speed of the turbopump. The pumping speed of the turbopump changes proportional to its rotation speed. Standby mode is ineffective during rotation speed setting mode. The set value in rotation speed setting mode **[P:707]** sets the set rotation speed. The rotation speed switch point varies with the set rotation speed. Underrunning or exceeding the set value in rotation speed setting mode activates or deactivates the status signal **[P:306] SetSpdAtt**.



#### Permissible variable rotation speed

Values in the rotation speed setting mode or standby mode are subject to the permissible rotation speed range of the respective vacuum pump (technical data). Underrunning the minimum permissible value leads to the warning message **Wrn100**. The electronic drive unit automatically adjusts the set rotation speed to the next valid value.

#### Set the rotation speed setting mode

1. Set the parameter **[P:707]** to the required value in %.
2. Set the parameter **[P:026]** to "1".
3. Check the set rotation speed (parameter **[P:308]** or **[P:397]**).

## 7.2.6 Standby

Pfeiffer Vacuum recommends standby mode for the turbopump during process and production stops. When standby mode is active, the electronic drive unit reduces the rotation speed of the turbo pump. Standby mode is ineffective during rotation speed setting mode. The factory setting for stand-by mode is 66.7 % of the nominal rotation speed. Underrunning or exceeding the set value in standby mode activates or deactivates the status signal **[P:306] SetSpdAtt**.



#### Permissible variable rotation speed

Values in the rotation speed setting mode or standby mode are subject to the permissible rotation speed range of the respective vacuum pump (technical data). Underrunning the minimum permissible value leads to the warning message **Wrn100**. The electronic drive unit automatically adjusts the set rotation speed to the next valid value.

#### Setting the related parameters

1. Set the parameter **[P:717]** to the required value in %.
2. Set the parameter **[P:026]** to "0".
3. Set the parameter **[P:002]** to "1".
4. Check the set rotation speed (parameter **[P:308]** or **[P:397]**).

## 7.2.7 Confirming the speed specification

The typical nominal rotation speed of a turbopump is preset at the factory in the electronic drive unit. If the electronic drive unit is replaced or a different pump type is used, the reference set value of the nominal rotation speed is cleared. The manual confirmation of the nominal rotation speed is part of a redundant safety system as a measure for preventing excess rotation speed.



HiPace	Confirmation of nominal rotation speed [P:777]
1200 / 1500	630 Hz
1800 / 2300	525 Hz
2800	455 Hz

**Tbl. 23: Characteristic nominal rotation speeds of the turbopumps**

#### Required aids

- A connected Pfeiffer Vacuum display and control unit.
- Knowledge of the configuration and setting of electronic drive unit operating parameters.

#### Adjusting the nominal rotation speed confirmation

The redundant confirmation of the nominal rotation speed of a turbopump is possible by adjusting the [P:777] **NomSpdConf** parameter in the electronic drive unit.

1. Observe the display and control unit operating instructions.
2. See the electronic drive unit operating instructions.
3. Set the parameter [P:794] to "1" and activate the expanded parameter set.
4. Open and edit the parameter [P:777].
5. Set the parameter [P:777] to the required value of the nominal rotation speed in Hertz.

**Alternative:** A Pfeiffer Vacuum SpeedConfigurator for the one-time immediate setting of parameter [P:777] is included with the replacement units.

## 7.2.8 Backing pump operating modes

Operation of a connected backing pump via the electronic drive unit depends on the backing pump type.

Operating mode [P:025]	Recommended booster pump
"0" Continuous operation	All backing pumps
"1" Interval mode	Diaphragm pumps only
"2" Delayed switching on	All backing pumps
"3" Delayed interval mode	Diaphragm pumps only

**Tbl. 24: Backing pump operating modes**

#### Setting continuous operation

With "pumping station on", the electronic drive unit sends a signal to the configured accessory connection to switch on the backing pump.

1. Set the parameter [P:025] to "0".
2. Use this signal for the control of a fore-vacuum safety valve.

#### Set interval operation and determine the switching threshold

Interval operation extends the service life of the diaphragm of a connected diaphragm pump. Either a diaphragm pump with a built-in semiconductor relay or an interconnected relay box with a semiconductor relay is required for interval operation. The electronic drive unit switches the backing pump on or off depending on the power consumption of the turbopump. A relationship to the fore-vacuum pressure results from the power consumption. The backing pump operating mode offers adjustable switch-on and switch-off thresholds. Fluctuations in the power consumption of idling turbopumps and varying fore-vacuum pressures of the backing pumps require individual settings of the interval operation.

Pfeiffer Vacuum recommends interval operation between 5 and 10 hPa. A pressure gauge and a dosing valve are required to set the switching thresholds.

1. Set the parameter [P:025] to "1".
2. Switch on the vacuum system with the parameter [P:010] ("pumping station").
3. Wait for the run-up.
4. Allow the gas to run via the dosing valve and set the fore-vacuum pressure to 10 hPa.
5. Read the drive power at parameter [P:316] and note the value.
6. Set the switch-on threshold of the backing pump with parameter [P:711] to the determined drive power for a 10 hPa fore-vacuum pressure.
7. Reduce the fore-vacuum pressure to 5 hPa.



8. Read the drive power at parameter **[P:316]** and note the value.
9. Set the switch-off threshold of the backing pump with parameter **[P:710]** to the determined drive power for a 5 hPa fore-vacuum pressure.

#### Delayed switching on

Simultaneous switching on of the backing pump and turbopump may cause undesired gas flow. To avoid this, depending on the process or application requirements, you can operate the backing pump with a delayed switch-on. The delayed switch-on depends on the rotation speed of the turbopump. The delayed switch-on has a fixed value of 360 rpm in the electronic drive unit.

- Switch-off threshold, parameter **[P:710]**
  - Switch-on threshold, parameter **[P:711]**
  - Delay 8 s.
1. Set the parameter **[P:025]** to "2".
  2. Use this signal for the control of a fore-vacuum safety valve.

#### Delayed interval operation

Fluctuations during the interval operation may lead to the underrunning or exceeding the switching thresholds. To avoid undesired switching of the backing pump you can operate the interval operation using a switching delay, depending on the process or application requirements. The delay is depending on a permanently uninterrupted exceedence or undershot of the specified switching threshold.

- Switch-off threshold, parameter **[P:710]**
  - Switch-on threshold, parameter **[P:711]**
  - Delay 8 s.
1. Set the parameter **[P:025]** to "3".
  2. Use this signal for the control of a fore-vacuum safety valve.

## 7.2.9 Backing pump standby mode

In case you are using a Pfeiffer Vacuum backing pump with rotation speed control, this can be used in standby mode by configuring the digital output **[P:019]** or **[P:024]**. The power consumption of the turbopump has a direct influence on the rotation speed of the backing pump.

#### Configuring the stand-by mode

1. Establish the connection of the backing pump using a suitable connecting cable.
2. Set parameter **[P:019]** or **[P:024]** to "22" (backing pump stand-by mode).
3. Find the respective standby rotation speed from the corresponding operating instructions of the backing pump.

## 7.2.10 Operation with accessories



#### Installation and operation of accessories

Pfeiffer Vacuum offers a series of special, compatible accessories for its products.

- Information and ordering options for approved [accessories](#) can be found online.
- The following accessories are not included in the scope of supply.

#### Configuring the heating

Activation of the connected housing heating depends on the rotation speed switch point 1 (factory setting  $80\% \times f_{Nominal}$ ).

- ▶ Switch the heating on or off with parameter **[P:001]**.

#### Configuring the sealing gas valve

- ▶ Using parameter **[P:050]**, switch a connected sealing gas valve on or off via the pre-configured output.

#### Monitoring the sealing gas

1. Set the selected parameter to "13".
2. Set the parameter **[P:791]** to the desired sealing gas flow for the warning threshold.
3. Query the sealing gas flow via parameter **[P:337]**.



## 7.2.11 Venting modes

The function "pumping station" enables the venting mode of the turbopump after switching off. The signal output is carried out with a fixed delay.

### Selecting the venting mode

1. Set parameter **[P:012]** to "1".
2. Select the venting mode with parameter **[P:030]** (3 possible modes).

### Delayed venting

1. Configure the beginning and the time for the venting after "pumping station off" depending on the rotation speed of the turbopump.
2. Set parameter **[P:030]** to "0".
3. With parameter **[P:720]**, set the venting speed to the nominal rotation speed in %.
4. With parameter **[P:721]**, set the venting speed in s.

The venting valve opens for the set venting time. In case of a power failure, the venting starts when underrunning the set venting speed. The venting period depends on the residual energy delivered by the turning rotor. The venting process stops, when power is restored.

### No venting

In this operating mode, the venting is deactivated.

- ▶ Set parameter **[P:030]** to "1".

### Direct venting

Venting starts with a delay of 6 s after "pumping station off". When the pumping station function is switched back on, the venting valve closes automatically. After a power failure, the venting starts after underrunning a fixed type-specific rotation speed. The venting process continues, when power is restored.

- ▶ Set parameter **[P:030]** to "2".

## 7.3 Operation via "remote" connection

### Operating the electronic drive unit remotely via "remote"

1. Remove the mating plug from the "remote" connection of the electronic drive unit.
2. Connect the remote control.
3. Observe the correct terminal lay-out.
4. Utilize the screened plug and cable.

### 7.3.1 +24 V DC output/pin 1

A connection with +24 VDC to pin 1 (active high) activates inputs 2–6, as well as the connections to pins 10, 13 and 14. Alternatively, they can be activated via an external PLC. "PLC High level" activates and "PLC Low level" deactivates the functions.

- PLC High level: +13 V to +33 V
- PLC High level: -33 V to +7 V
- Ri: 7 kΩ
- $I_{\max} < 210$  mA (with RS-485, where present)

### 7.3.2 Inputs

The digital inputs at the "remote" connection are used to switch various electronic drive unit functions. As a factory default, inputs DI1 – DI2 have functions that you can configure with the Pfeiffer Vacuum parameter set via the RS-485 interface.

#### DI1 (release venting) / Pin 2

Status	Description
V+	Release venting (venting as per venting mode)
open	Venting blocked (no venting occurs)

Tbl. 25: DI1 (release venting) / Pin 2



**DI motor pump/pin 3**

With pin 4 activated (pumping station) and successfully completed self-test of the electronic drive unit, the turbopump is initiated. During operation the turbopump can be switched off and back on again, with the pumping station still active, without venting the turbopump.

Status	Description
V+	Turbo pump motor on
open	Turbo pump motor off

**Tbl. 26: DI motor pump/pin 3**

**DI pumping station / Pin 4**

Control of connected pumping station components (e.g. backing pump, venting valve, air cooling). If pin 3 (motor) is activated at the same time, the turbopump starts up. Any pending error messages are reset by eliminating the cause.

Status	Description
V+	Malfunction acknowledgement and pumping station on
open	Pumping station off

**Tbl. 27: DI pumping station / Pin 4**

**DI standby/pin 5**

In standby mode, the turbo pump operates at a specified rotor speed < nominal rotation speed. The factory setting and recommended operation is 66.7 % of the nominal rotation speed.

Status	Description
V+	Standby activated
open	Standby off, operation at nominal rotation speed

**Tbl. 28: DI standby/pin 5**

**DI2 (heater)/pin 6**

Status	Description
V+	Heater on
open	Heater off

**Tbl. 29: DI2 (heater)/pin 6**

**DI3 (sealing gas)/pin 10**

Status	Description
V+	Sealing gas valve open
open	Sealing gas valve closed

**Tbl. 30: DI3 (sealing gas)/pin 10**

**DI malfunction acknowledgment/pin 13**

Status	Description
V+	Reset pending error messages when cause has been eliminated with a pulse of min. 500 ms duration.
open	Inactive

**Tbl. 31: DI malfunction acknowledgment/pin 13**



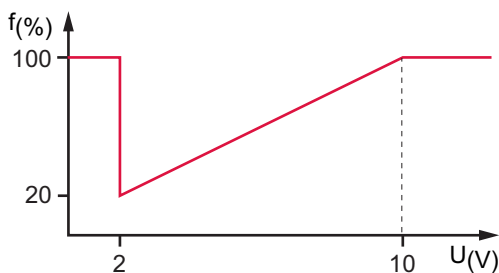


**DI remote priority/pin 14**

Status	Description
V+	The "remote" connection has control priority over all other digital inputs.
open	Remote priority inactive

**Tbl. 32: DI remote priority/pin 14****AI speed setting operation/pins 7 and 11**

The analog input serves as a rotation speed setpoint for the turbopump. An input signal of 2 to 10 V between AI+ (pin 7) and AI- (pin 11) corresponds to a speed within the range of 20 to 100% of the nominal rotation speed. If the input is open or signals are below 2 V, the turbopump accelerates to the nominal rotation speed.

**Fig. 9: Speed actuator operation****7.3.3 Outputs**

The digital outputs at the "remote" connection have a maximum load limit of 24 V/50 mA per output. All outputs listed below are configurable with the Pfeiffer Vacuum parameter set via the RS485 interface (description relates to factory settings).

**DO1 (rotation speed switchpoint reached) / Pin 8**

Active high: After reaching the rotation speed switch point. Rotation speed switchpoint 1 has a factory setting of 80% of the nominal rotation speed. This can be used, for example, for a "Pump ready for operation" message.

**DO2 (no error)/pin 9**

When the supply voltage has been connected, digital output DO2 permanently outputs 24 V DC, which means "no error". Active low: in case of error (group error message).

**DI remote priority active/pin 23**

Active high: The "remote" connection takes priority over all other potentially connected control units (e.g. RS-485). For active low, the electronic drive unit ignores the "remote" connection.

**AO1 analog output 0 to 10 V DC/pin 12**

You can tap a speed-proportional voltage (0 to 10 V DC equals 0 to 100%  $\times f_{\text{nominal}}$ ) at the analog output (load  $R \geq 10 \text{ k}\Omega$ ). Additional functions (optionally current/power) can be assigned to the analog output via DCU, HPU or PC.

**7.3.4 Relay contacts (invertible)****Relay 1/pins 15, 16 and 17**

The contact between pin 16 and pin 15 is closed when the rotation speed drops below the switchpoint; relay 1 is inactive. The contact between pin 16 and pin 17 is closed when the speed reaches the rotation speed switchpoint; relay 1 is active.

**Relay 2/pins 18, 19 and 20**

The contact between pin 19 and pin 18 is closed when an error is pending; relay 2 is inactive. The contact between pin 19 and pin 20 is closed in case of trouble-free operation; relay 2 is active.

**Relay 3/pins 21 and 22**

The contact between pin 21 and pin 22 is closed in case of inactive warning messages; relay 3 is inactive. The contact between pin 21 and pin 22 is open when warnings are pending; relay 3 is active.



### 7.3.5 RS-485

#### **⚠ DANGER**

##### **Danger to life from electric shock**

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.

A Pfeiffer Vacuum display and control unit (DCU **or** HPU) **or** an external PC can be connected via pins 24 and 25 of the electronic drive unit's "remote" connection. A USB interface (PC) can be connected via the USB/RS-485-converter.

Designation	Value
Serial interface	RS-485
Baudrate	9600 Baud
Data word length	8 bit
Parity	none (no parity)
Start bits	1
Stop bits	1 – 2

**Tbl. 33: RS-485 interface, features**

#### **Networking as RS-485 Bus**

The group address of the electronic drive unit is 963.

1. Install the devices according to the specification for RS-485 interfaces.
2. Make sure that all devices connected to the bus have different RS-485 device addresses **[P:797]**.
3. Connect all devices to the bus with RS-485 D+ and RS-485 D-.

## 7.4 Switching on the turbopump

The function "pumping station" **[P:010]** comprises the turbopump operation with control of all connected accessory devices (e.g. backing pump).

#### **Procedure**

After successfully completing the self-test, the electronic drive unit resets pending and corrected error messages. The turbopump starts and all connected accessory devices start operation according to their configuration.

1. Set the parameter **[P:023]** to "1".
  - The parameter **[P:023]** switches on the motor of the turbopump.
2. Set the parameter **[P:010]** to "1".

## 7.5 Switching off the turbopump

#### **Procedure**

The electronic drive unit switches off the turbopump and activates pre-set accessory options (e.g. venting ON, backing pump OFF).












1. Set the parameter **[P:010]** to "0".
2. Wait until the turbopump comes to a complete standstill.
3. Disconnect the power supply according to the operating instructions of the turbopump or the power supply pack.



## 7.6 Operation monitoring

### 7.6.1 Operating mode display via LED

LEDs on the electronic drive unit show the basic operating states of the vacuum pump. A differentiated error and warning display is only possible for operation with the Pfeiffer Vacuum display and control unit or a PC.

LED	Symbol	LED status	Display	Meaning
Green 		Off	—	Currentless
		On, flashing		"pumping station OFF", rotation speed $\leq 60$ rpm
		On, inverse flashing		"pumping station ON", set rotation speed not reached
		On, constant		"pumping station ON", set rotation speed reached
		On, flashing		"pumping station OFF", speed $> 60$ rpm
Yellow 		Off	—	No warning
		On, constant		Warning
Red 		Off	—	No error, no warning
		On, constant		Error, malfunction

Tbl. 34: Behavior and meaning of the LEDs on the electronic drive unit

### 7.6.2 Temperature monitoring

If threshold values are exceeded, output signals from temperature sensors bring the turbopump to a safe condition. Depending on the type, temperature thresholds for warning and error messages are immutably stored in the electronic drive unit. For information purposes, various status requests are set up in the parameter set.

- In order to avoid switching off the turbopump, the electronic drive unit already reduces the power consumption in case of exceeding the warning threshold for excess temperature.
  - Examples are an impermissible motor temperature, or impermissibly high housing temperature.
- Further reduction of drive power and thus decreasing speed can potentially lead to underrun the rotation speed switchpoint. The turbopump switches off.
- Exceeding the temperature threshold for error messages switches off the turbopump immediately.



## 8 Malfunctions

### 8.1 General

#### **WARNING**

##### **Risk of injury from parts moving after a power failure or troubleshooting**

The "pumping station" function of the electronic drive unit will remain active after a power failure or if errors occur that shut down the vacuum pump or the system. When power is restored or after acknowledging a fault, the vacuum pump runs up automatically. There is a risk of injury to fingers and hands if they enter the operating range of rotating parts.

- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.
- ▶ Remove present mating plugs or bridges from the electronic drive unit possibly before the mains power returns, as these can cause an automatic run-up.
- ▶ Switch the pump off using the "Pumping station" function (parameter **[P:010]**).


Malfunctions of turbopump and electronic drive unit always result in a warning or error messages. In both cases, you receive an error code that you can read out via the interfaces of the electronic drive unit. Generally, the LEDs on the electronic drive unit show the operating messages. If an error occurs, the turbo pump and connected devices switch off. The selected venting mode starts after a preset delay.

### 8.2 Error codes

Errors (\*\* Error E—— \*\*) always cause the connected peripheral devices to be switched off.

Warnings (\* Warning F —— \*) do not cause components to be switched off.

#### **Handling malfunction messages**

1. Read out the error codes via the display and control panel or the PC.
2. Remove the cause of the malfunction.
3. Reset the error message with parameter **[P:009]** or by pressing the button  on the DCU.

Error code	Problem	Possible causes	Remedy
Err001	Excess rotation speed	<ul style="list-style-type: none"> <li>• Device defective</li> </ul>	<ul style="list-style-type: none"> <li>• Contact Pfeiffer Vacuum Service.</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err002	Excess voltage	<ul style="list-style-type: none"> <li>• Incorrect power supply pack</li> <li>• Incorrect mains input voltage</li> </ul>	<ul style="list-style-type: none"> <li>• Check the power supply pack type</li> <li>• Check the mains input voltage</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err006	Run-up error	<ul style="list-style-type: none"> <li>• Run-up time threshold set too low</li> <li>• Gas flow in recipients through leaks or open valves</li> <li>• Still below speed-control switch point run-up time expires</li> </ul>	<ul style="list-style-type: none"> <li>• Adjust the run-up time to the process conditions</li> <li>• Check the vacuum chambers for leaks and closed valves</li> <li>• Adjust the rotation speed switch point</li> </ul>
Err007	Operating fluid low	<ul style="list-style-type: none"> <li>• Operating fluid low</li> </ul>	<ul style="list-style-type: none"> <li>• Check the operating fluid</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err008	Electronic drive unit - turbopump connection faulty	<ul style="list-style-type: none"> <li>• Connection to turbopump faulty</li> </ul>	<ul style="list-style-type: none"> <li>• Check the connections</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err010	Internal device error	<ul style="list-style-type: none"> <li>• Device defective</li> </ul>	<ul style="list-style-type: none"> <li>• Contact Pfeiffer Vacuum Service.</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err021	Electronic drive unit does not detect turbopump	<ul style="list-style-type: none"> <li>• Incompatible software version</li> <li>• Device defective</li> </ul>	<ul style="list-style-type: none"> <li>• Contact Pfeiffer Vacuum Service.</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>
Err041	Drive fault	<ul style="list-style-type: none"> <li>• Device defective</li> </ul>	<ul style="list-style-type: none"> <li>• Contact Pfeiffer Vacuum Service.</li> <li>• Only acknowledge for rotational speed f = 0</li> </ul>



Error code	Problem	Possible causes	Remedy
Err043	Internal configuration error	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err044	Excess temperature, electronics	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Err045	Excess temperature, motor	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Err046	Internal initialization error	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err073	Axial magnetic bearing overload	<ul style="list-style-type: none"> <li>Rate of pressure rise too high</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err074	Radial magnetic bearing overload	<ul style="list-style-type: none"> <li>Rate of pressure rise too high</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err089	Rotor instable	<ul style="list-style-type: none"> <li>Impacts, vibrations</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err091	Internal device error	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err092	Unknown connection panel	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err093	Motor temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err094	Electronics temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err098	Internal communication error	<ul style="list-style-type: none"> <li>External faults</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err107	Final stage group error	<ul style="list-style-type: none"> <li>External faults</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err108	Rotation speed measurement faulty	<ul style="list-style-type: none"> <li>External faults</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err109	Software not released	<ul style="list-style-type: none"> <li>Faulty software update</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err110	Operating fluid evaluation faulty	<ul style="list-style-type: none"> <li>Operating fluid sensor faulty</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err111	Operating fluid pump communication error	<ul style="list-style-type: none"> <li>External faults</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err112	Operating fluid pump group error	<ul style="list-style-type: none"> <li>External faults</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err113	Rotor temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err114	Final stage temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err117	Excess temperature, pump lower part	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Err118	Excess temperature, final stage	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Err119	Excess temperature, bearing	<ul style="list-style-type: none"> <li>Insufficient cooling</li> <li>Incorrect gas mode selected</li> <li>Insufficient sealing gas flow</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Err143	Operating fluid pump excess temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err777	Nominal rotation speed not confirmed	<ul style="list-style-type: none"> <li>Nominal rotation speed not confirmed after replacing the electronic drive unit</li> </ul>	<ul style="list-style-type: none"> <li>Confirm the nominal rotation speed with <b>[P:777]</b></li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err800	Magnetic bearing overflow	<ul style="list-style-type: none"> <li>Impacts, vibrations</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Check the operating conditions</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err802	Magnetic bearing sensor technology fault	<ul style="list-style-type: none"> <li>Calibration values invalid</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Perform a calibration procedure</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>



Error code	Problem	Possible causes	Remedy
Err810	Internal configuration error	<ul style="list-style-type: none"> <li>Incompatible software version</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err815	Magnetic bearing overflow	<ul style="list-style-type: none"> <li>Impacts, vibrations</li> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Check the operating conditions</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>
Err890	Safety bearing worn	<ul style="list-style-type: none"> <li>Safety bearing wear &gt; 100%</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Err891	Rotor imbalance too high	<ul style="list-style-type: none"> <li>Rotor imbalance &gt; 100%</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Only acknowledge for rotational speed <math>f = 0</math></li> </ul>

Tbl. 35: Error messages of the electronic drive unit

Error code	Problem	Possible causes	Remedy
Wrn001	TMS heat-up time expired	<ul style="list-style-type: none"> <li>Internal timer for heat-up monitoring exceeded</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> <li>Check the mains input voltage</li> </ul>
Wrn003	TMS temperature invalid	<ul style="list-style-type: none"> <li>TMS temperature not in the permissible range between 5 °C and 85 °C</li> <li>TMS temperature sensor defective</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn007	Undervoltage or power failure	<ul style="list-style-type: none"> <li>Mains failure</li> <li>Power supply pack dimensioned insufficiently</li> </ul>	<ul style="list-style-type: none"> <li>Check the power supply pack type</li> <li>Check the mains input voltage</li> </ul>
Wrn016	Accessory configuration invalid	<ul style="list-style-type: none"> <li>Impermissible configuration of the accessory outputs</li> </ul>	<ul style="list-style-type: none"> <li>Check the configuration of all accessory outputs</li> </ul>
Wrn018	Operating supremacy conflict	<ul style="list-style-type: none"> <li>Pumping station switched on with <b>[P:010]</b> while E74 input "start/stop" is off (opened)</li> </ul>	<ul style="list-style-type: none"> <li>Switch on the pumping station via E74 "start/stop"</li> <li>Switch <b>[P:010]</b> off</li> </ul>
Wrn021	Blocking signal invalid	<ul style="list-style-type: none"> <li>Signal of the blocking signal monitoring outside the valid range</li> </ul>	<ul style="list-style-type: none"> <li>Check the connections of the sealing gas monitoring</li> <li>Check the sealing gas supply</li> </ul>
Wrn034	Sealing gas flow too low	<ul style="list-style-type: none"> <li>Signal of the sealing gas monitoring valid but below the set threshold <b>[P:791]</b></li> </ul>	<ul style="list-style-type: none"> <li>Check and improve the sealing gas supply</li> </ul>
Wrn045	Motor high temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Wrn076	Electronics high temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Wrn089	Imbalance high	<ul style="list-style-type: none"> <li>Rotor imbalance</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn097	Invalid pump information	<ul style="list-style-type: none"> <li>Internal communication error</li> </ul>	<ol style="list-style-type: none"> <li>Shut down pumping station</li> <li>Wait until the turbopump comes to a standstill</li> <li>Disconnect the power supply</li> <li>If this reoccurs, contact Pfeiffer Vacuum Service</li> </ol>
Wrn098	Incomplete pump information	<ul style="list-style-type: none"> <li>Internal communication error</li> </ul>	<ol style="list-style-type: none"> <li>Shut down pumping station</li> <li>Wait until the turbopump comes to a standstill</li> <li>Disconnect the power supply</li> <li>If this reoccurs, contact Pfeiffer Vacuum Service</li> </ol>
Wrn100	Minimum speed not reached	<ul style="list-style-type: none"> <li>Settings of the set rotation speed below the pump-specific minimum speed</li> </ul>	<ul style="list-style-type: none"> <li>Check <b>[P:707]</b> or <b>[P:717]</b></li> <li>Obtain the valid rotation speed range from the technical data of the turbopump</li> </ul>
Wrn106	High rotor temperature	<ul style="list-style-type: none"> <li>High gas throughput</li> <li>Impermissible thermal radiation</li> <li>Impermissible magnetic field</li> </ul>	<ul style="list-style-type: none"> <li>Check the operating conditions</li> </ul>
Wrn113	Inaccurate rotor temperature	<ul style="list-style-type: none"> <li>Internal communication error</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>



Error code	Problem	Possible causes	Remedy
Wrn115	Pump lower part temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn116	Bearing temperature evaluation faulty	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn117	Pump lower part high temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> <li>Incorrect gas mode selected</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Wrn118	Final stage high temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> <li>Incorrect gas mode selected</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Wrn119	Bearing high temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> <li>Incorrect gas mode selected</li> <li>Insufficient sealing gas flow</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> <li>Check the operating conditions</li> </ul>
Wrn143	High operating fluid pump temperature	<ul style="list-style-type: none"> <li>Insufficient cooling</li> </ul>	<ul style="list-style-type: none"> <li>Improve the cooling</li> </ul>
Wrn168	High delay	<ul style="list-style-type: none"> <li>Rate of pressure rise too high</li> <li>Venting rate too high</li> </ul>	<ul style="list-style-type: none"> <li>Check the venting rate</li> <li>Adapt the venting rate to the pump</li> </ul>
Wrn801	Braking transistor defective	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn806	Brake resistance defective	<ul style="list-style-type: none"> <li>Device defective</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn807	Calibration requirement	<ul style="list-style-type: none"> <li>Calibration expired</li> </ul>	<ul style="list-style-type: none"> <li>Calibrate the turbopump by starting from standstill</li> </ul>
Wrn890	Safety bearing wear too high	<ul style="list-style-type: none"> <li>Safety bearing wear &gt; 75 %</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
Wrn891	High rotor imbalance	<ul style="list-style-type: none"> <li>Rotor imbalance &gt; 75 %</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>

**Tbl. 36: Warning messages of the electronic drive unit**

### 8.3 Warning and error messages when operating with DCU

Besides the device-specific warning and error messages on the electronic drive unit, additional messages are displayed with the connected display and control panel.

Display in DCU	Problem	Possible causes	Remedy
* Warning F110 *	Pressure gauge	<ul style="list-style-type: none"> <li>Pressure gauge faulty</li> <li>Connection to the pressure gauge disconnected during operation</li> </ul>	<ul style="list-style-type: none"> <li>Check the cable connection</li> <li>Carry out a restart with pressure gauge connected</li> <li>Replace the pressure gauge completely</li> </ul>
** Error E040 **	Hardware error	<ul style="list-style-type: none"> <li>external RAM faulty</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
** Error E042 **	Hardware error	<ul style="list-style-type: none"> <li>EPROM checksum incorrect</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
** Error E043 **	Hardware error	<ul style="list-style-type: none"> <li>E<sup>2</sup>PROM write error</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>
** Error E090 **	Internal device error	<ul style="list-style-type: none"> <li>RAM not large enough</li> <li>DCU is connected to incorrect electronic drive unit</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> <li>Connect the DCU to the correct electronic drive unit</li> </ul>
** Error E698 **	Communication error	<ul style="list-style-type: none"> <li>Electronic drive unit is not responding</li> </ul>	<ul style="list-style-type: none"> <li>Contact Pfeiffer Vacuum Service.</li> </ul>

**Tbl. 37: Warning and error messages when using a DCU**



## 9 Service solutions from Pfeiffer Vacuum

### We offer first class service

Long vacuum component service life, coupled with low downtimes, are clear expectations that you have of us. We satisfy your needs with capable products and outstanding service.

We are consistently striving to perfect our core competence, service for vacuum components. And our service is far from over once you've purchased a product from Pfeiffer Vacuum. It often enough really just begins then. In proven Pfeiffer Vacuum quality, of course.

Our professional sales engineers and service technicians stand ready to provide hands-on support to you worldwide. Pfeiffer Vacuum offers a complete portfolio of service offerings, ranging from genuine spare parts right through to service agreements.

### Take advantage of Pfeiffer Vacuum Service

Whether for preventative on-site service from our field service, fast replacement with as-new replacement products or repair in a Service Center close to you; you have various options for upholding your equipment availability. Detailed information and addresses can be found on our website in the Pfeiffer Vacuum Service section.

### Advice on the optimum solution is available from your Pfeiffer Vacuum contact partner.

**For quick and smooth handling of the service process, we recommend the following steps:**



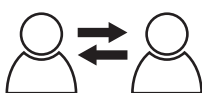
1. Download the current form templates.
  - [Declaration of Service Request](#)
  - [Service Request](#)
  - [Declaration of Contamination](#)



- a) Dismantle all accessories and keep them (all external mounted parts as valve, inlet screen, etc.).
  - b) Drain the operating fluid/lubricant as necessary.
  - c) Drain the cooling medium as necessary.
2. Fill out the service request and the declaration of contamination.



3. Send the forms via email, fax or post to your local Service Center.



4. You will receive a response from Pfeiffer Vacuum.

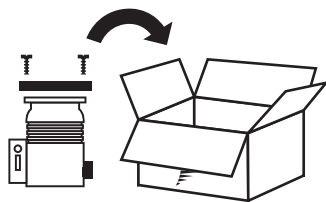
PFEIFFER VACUUM

### Sending of contaminated products

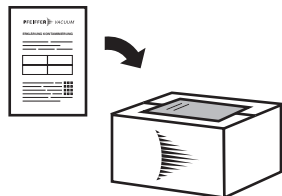
No units will be accepted if they are contaminated with micro-biological, explosive or radioactive substances. If products are contaminated or if the declaration of contamination is missing, Pfeiffer Vacuum will contact the customer before starting maintenance. In addition, depending on the product and the level of contamination **additional decontamination costs** may be required.



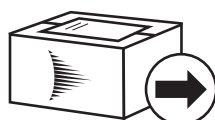




5. Prepare the product for transport in accordance with the details in the declaration of contamination.
  - a) Neutralize the product with nitrogen or dry air.
  - b) Close all openings with airtight blank flanges.
  - c) Seal the product in appropriate protective film.
  - d) Only pack the product in suitable, stable transport containers.
  - e) Observe the applicable transport conditions.



6. Affix the declaration of contamination to the **outside** of the packaging.



7. Then send your product to your local Service Center.



8. You will receive a confirmation message/a quotation from Pfeiffer Vacuum.

PFEIFFER VACUUM

For all service orders, our General Terms and Conditions of Sales and Supply and General Terms and Conditions of Repair and Maintenance apply to vacuum equipment and components.



# Declaration of conformity

Declaration for product(s) of the type:

**Electronic drive unit**

TC 1200

We hereby declare that the listed product satisfies all relevant provisions of the following **European Directives**.

**Electromagnetic compatibility 2014/30/EU**

**Low voltage 2014/35/EC**

**Restriction of the use of certain hazardous substances 2011/65/EU**

**Restriction of the use of certain hazardous substances, delegated directive 2015/863/EU**

**Harmonized standards and applied national standards and specifications:**

DIN EN 61000-3-2: 2014

DIN EN 61000-3-3: 2013

DIN EN 61010-1: 2011

DIN EN 61326-1: 2013

DIN EN 62061: 2013

DIN EN IEC 63000: 2019

Semi F47-0200

Semi S2-0706

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Signature:



(Daniel Sälzer)  
Managing Director

Pfeiffer Vacuum GmbH  
Berliner Straße 43  
35614 Asslar  
Germany

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Asslar, 2019-07-18





## VACUUM SOLUTIONS FROM A SINGLE SOURCE

Pfeiffer Vacuum stands for innovative and custom vacuum solutions worldwide, technological perfection, competent advice and reliable service.

## COMPLETE RANGE OF PRODUCTS

From a single component to complex systems:

We are the only supplier of vacuum technology that provides a complete product portfolio.

## COMPETENCE IN THEORY AND PRACTICE

Benefit from our know-how and our portfolio of training opportunities!

We support you with your plant layout and provide first-class on-site service worldwide.

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perfect vacuum solution?  
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